

Scalar Product, Dot Product

↳ is a scalar → has magnitude (number & units) but No direction.

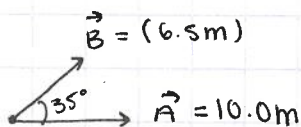
* Definition of $\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta$

$|\vec{A}|$ → magnitude of A

$|\vec{B}|$ → magnitude of B

θ → Angle between \vec{A} & \vec{B} (less than 180°)

Ex

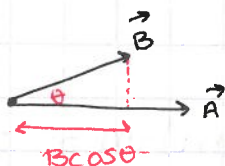


$\vec{A} \cdot \vec{B} = (10.0m)(6.5m) \cos 35^\circ$

* $\hat{i}, \hat{j}, \hat{k}$: $|\hat{i}| = |\hat{j}| = |\hat{k}| = 1$

angle between $\hat{i} + \hat{k}, \hat{i} + \hat{j}, \hat{j} + \hat{k}, \dots = 90^\circ$

$\hat{i} + \hat{i}, \hat{j} + \hat{j}, \hat{k} + \hat{k} = 0^\circ$



conceptually → $\vec{A} \cdot \vec{B}$ is magnitude of A times how much of \vec{B} points in the direction of \vec{A}

$\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = (1)(1) \cos 0^\circ = 1$

$\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} = \hat{i} \cdot \hat{k} = \hat{k} \cdot \hat{j} = \hat{j} \cdot \hat{i} = (1)(1) \cos 90^\circ = 0$

RECAP

MARCH 19, 2019

Scalar or Dot product of 2 vectors

$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta$

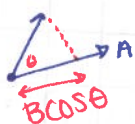
$|\vec{A}|$ → magnitude of vector \vec{A}

$|\vec{B}|$ → magnitude of vector \vec{B}

θ → Angle between \vec{A} and \vec{B}

ch 8

March 19, 2019

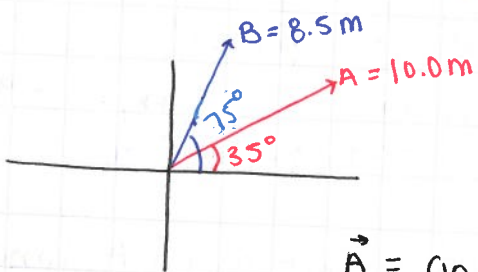


$$\vec{A} \cdot \vec{B} = (\text{length of } \vec{A}) \times (\text{length of } \vec{B} \text{ in direction of } \vec{A})$$

unit vectors $\rightarrow \hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = (1)(1) \cos 0^\circ = 1$
 $\hat{i} \cdot \hat{j} = \hat{i} \cdot \hat{k} = \hat{j} \cdot \hat{k} = \hat{j} \cdot \hat{i} = \hat{k} \cdot \hat{i} = \hat{k} \cdot \hat{j} = (1)(1) \cos 90^\circ = 0$

$$\begin{aligned} \vec{A} \cdot \vec{B} &= (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k}) \\ &= A_x B_x \hat{i} \cdot \hat{i} + A_y B_y \hat{j} \cdot \hat{j} + A_z B_z \hat{k} \cdot \hat{k} \\ &\quad + A_y B_x \hat{j} \cdot \hat{i} + A_x B_y \hat{i} \cdot \hat{j} + A_z B_x \hat{k} \cdot \hat{i} + A_x B_z \hat{i} \cdot \hat{k} \\ &\quad + A_z B_y \hat{k} \cdot \hat{j} + A_y B_z \hat{j} \cdot \hat{k} \end{aligned}$$

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$



$$\begin{aligned} \vec{A} \cdot \vec{B} &= |\vec{A}| |\vec{B}| \cos \theta \\ &= (10.0\text{m})(8.5\text{m}) \cos 40^\circ \\ &= \underline{65.1\text{m}^2} \end{aligned}$$

$$\begin{aligned} \vec{A} &= (10.0\text{m}) \cos 35^\circ \hat{i} + (10.0\text{m}) \sin 35^\circ \hat{j} \\ &= (8.19\text{m}) \hat{i} + (5.74\text{m}) \hat{j} \\ \vec{B} &= (8.5\text{m}) \cos 75^\circ \hat{i} + (8.5\text{m}) \sin 75^\circ \hat{j} \\ &= (2.20\text{m}) \hat{i} + (8.21\text{m}) \hat{j} \end{aligned}$$

$$\begin{aligned} \vec{A} \cdot \vec{B} &= A_x B_x + A_y B_y + A_z B_z \\ &= (8.19\text{m})(2.20\text{m}) + (5.74\text{m})(8.21\text{m}) \\ &= \underline{65.1\text{m}^2} \end{aligned}$$

Reason we care $\rightarrow W = \vec{F} \cdot (\Delta \vec{r})$

Problem 9.11A

$$\vec{A} = 4\hat{i} - 2\hat{j} \text{ and } \vec{B} = -2\hat{i} - 3\hat{j}$$

$$(4)(-2) + (-2)(-3) = \underline{\underline{-2}}$$

Problem 9.15

c) Angle is 90° , this means that the answer is 0°

d) $|A||B|\cos\theta$

$$(3)(5)\cos 40^\circ = \underline{\underline{11.5}}$$

CH.9: Work & Kinetic Energy

- Energy overview

What is Energy?

↳ That property of an object or system that enables it to do work

Exerting a force on an object over a distance

System → defined collection of objects whose interactions we wish to study

Environment → Everything that is NOT part of the System

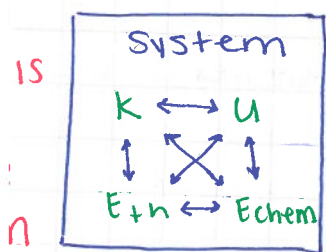
Internal forces → forces that objects within the System exert on each other

March 19, 2018

Internal forces → forces that objects in the environment exert on objects within the system

Basic Energy Model

Environment



$w < 0$
Energy is removed from the system

Energy within a system is transformed without loss (i.e. $U \rightarrow K \rightarrow E_{chem}$)

Energy can be transferred to or from the System by forces from the environment

- The forces do work on the system
- $w > 0$ if energy is added to the system
- $w < 0$ if energy is removed from the system

change in the

energy of the system

$$\Delta E_{system} = W_{ext}$$

→ work done by external forces

for an isolated system ($w_{ext} = 0$), $\Delta E_{system} = 0$

$$(E_{system})_f = (E_{system})_i$$

ch 9.

March 19, 2019

Forms of Energy:

$K \rightarrow$ kinetic energy (energy of motion)

$$K = \frac{1}{2}mv^2$$

$U_g \rightarrow$ gravitational potential energy (stored energy associated with an object's height)

$$U_g = mgy$$

$U_{sp} \rightarrow$ Elastic or spring potential energy (energy stored when an elastic object is stretched or compressed)

$$U_{sp} = \frac{1}{2}kx^2$$

$k \rightarrow$ spring constant

$x \rightarrow$ how much spring is stretched or compressed

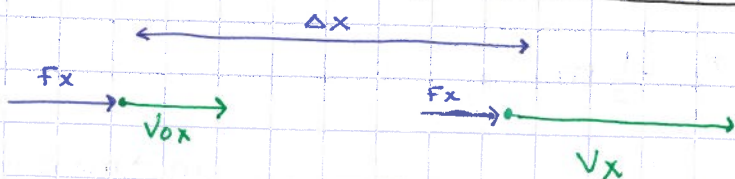
$E_{th} \rightarrow$ thermal energy (sum of kinetic & potential energies of all the atoms & molecules in an object)

$$\Delta E_{th} = -f_k \cdot \Delta r$$

$E_{chem} \rightarrow$ chemical energy (Energy stored in the bonds between atoms & molecules)

\rightarrow Energy gets released when bonds are broken and/or rearranged.

WORK & K.E. for a single particle (acted upon by a single force)



constant force F_x acting on an object over a displacement of Δx resulting in speed increasing

Ch 9

March 19, 2019

$$\sum \vec{F} = m\vec{a}$$

) one-dimensional motion

$$\sum F_x = ma_x \rightarrow F_x = ma_x \text{ (only one force)}$$

$$F_x = m \frac{dv_x}{dt}$$

$$\frac{dv_x}{dt} = \frac{dv_x}{dx} \frac{dx}{dt}$$

$$= \frac{dv_x}{dx} v_x$$

$$F_x = m \left(\frac{dv_x}{dx} \right) v_x$$

$$F_x = m v_x \frac{dv_x}{dx}$$

$$F_x dx = m v_x dv_x$$

$$\int_{x_0}^x F_x dx = \int_{v_{0x}}^{v_x} m v_x dv_x$$

$$= m \int_{v_{0x}}^{v_x} v_x dv_x$$

$$= m \left[\frac{1}{2} v_x^2 \right] \Big|_{v_{0x}}^{v_x}$$

$$= \frac{1}{2} m v_x^2 - \frac{1}{2} m v_{0x}^2$$

$$\int_{x_0}^x F_x dx = \frac{1}{2} m v_x^2 - \frac{1}{2} m v_{0x}^2$$

KINETIC ENERGY $K = \frac{1}{2} m v^2$

$m \rightarrow$ mass in kg
 $v \rightarrow$ speed in m/s
(Not velocity)

ch 9

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$$[K] = \frac{\text{kg m}^2}{\text{s}^2} = (\text{kg m/s}^2)\text{m} = \text{Nm} = \text{joule (J)}$$

$$1 \text{ J} = 1 \text{ Nm} = 1 \frac{\text{kg m}^2}{\text{s}^2}$$

$$\int_{x_0}^x F_x dx = \Delta K = K_f - K_i$$
$$= \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

→ change in kinetic energy

↓
How work is defined

$$W = \int_{x_0}^x F_x dx$$

→ work = Area under the curve of F vs x

ch 9

March 19, 2019

$$[K] = \frac{\text{kg m}^2}{\text{s}^2} = (\text{kg m/s}^2)\text{m} = \text{Nm} = \text{joule (J)}$$

$$1 \text{ J} = 1 \text{ Nm} = \frac{1 \text{ kg m}^2}{\text{s}^2}$$

$$\int_{x_0}^x F_x dx = \Delta K = K_f - K_i = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

→ change in kinetic energy

How work is defined

$$W = \int_{x_0}^x F_x dx \rightarrow \text{WORK} = \text{Area under the curve of } F \text{ vs } x$$

RECAP

March 21, 2019

Dot product or scalar product:

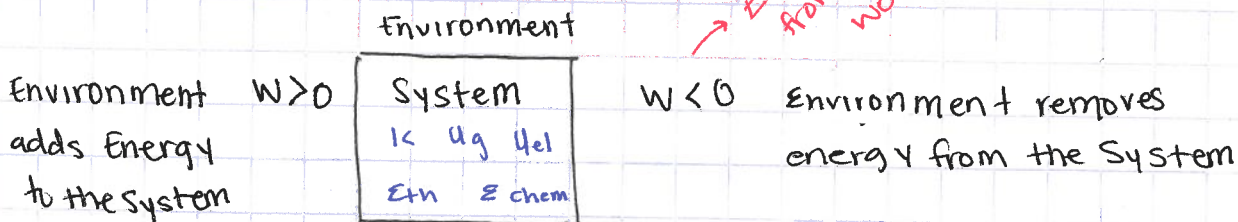
$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta \rightarrow \text{definition of } \vec{A} \cdot \vec{B}$$

$$\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$$

$$\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} = \hat{i} \cdot \hat{k} = \hat{k} \cdot \hat{j} = \hat{j} \cdot \hat{i} = 0$$

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

Basic Energy Model



→ Energy is transferred to or from a system by doing work on it.

↓ Inside a system energy is transformed without loss.

$$\Delta E_{\text{system}} = W_{\text{exp}}$$

↓
Change in total energy of the system.

↘ Work done by external forces

Work + KE for a single particle

$$\int_{x_0}^x F_x dx = \frac{1}{2} m v_x^2 - \frac{1}{2} m v_{0x}^2$$

$$\int_{x_i}^{x_f} F_x dx = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

↓
work done by external forces as object is displaced from x_0 to x

$[K] = [W] = \text{Joule (J)}$
 $1 \text{ J} = 1 \text{ Nm} = 1 \text{ kg m}^2/\text{s}^2$

Kinetic Energy

$$K = \frac{1}{2} m v^2$$

$v = \text{speed, not velocity}$

$$\int_{x_0}^x F_x dx = \Delta K = K_f - K_i$$

→ change in kinetic energy of object

$1 \text{ cal} = 4.186 \text{ J}$
 $1 \text{ Cal} = 1 \text{ kcal}$

* The work done on a one-particle system causes the kinetic energy of the particle to change

$$\int_{x_0}^x F_x dx = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

W_{ext}

ΔK

→ Derived for a one-particle system but applies to any system.

$W_{total} = W_1 + W_2 + \dots$ total work done by all forces
 $K_{total} =$ total KE of all objects in the system = $K_1 + K_2 + \dots$

Problem 9.21

$$W = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

$$m = 0.500 \text{ kg}$$

$$v_i = 2.0 \text{ m/s}$$

↓
Area under the curve

= Area of rectangle (0-1m) + Area of triangle (1m-3m)

$$= (1\text{m})(15\text{N}) + \frac{1}{2}(2\text{m})(15\text{N}) = 15\text{J} + 15\text{J} = 30\text{J}$$

$$\frac{1}{2} m v_f^2 = W + \frac{1}{2} m v_i^2 \rightarrow v_f^2 = \frac{2W}{m} + v_i^2 \rightarrow v_f = \sqrt{\frac{2W}{m} + v_i^2}$$

$$v_f = \sqrt{\frac{2W}{m} + v_i^2} = \sqrt{\frac{2(30\text{J})}{0.500\text{kg}} + (2.0\text{m/s})^2}$$

$$v_f = 11 \text{ m/s (speed)} \quad \vec{v} = +11 \text{ m/s}$$

Work done by a constant force



$$\begin{aligned}
 W &= \int_{x_0}^x F_x dx \\
 &= \int_{x_0}^x (F \cos \theta) dx \\
 &= F \cos \theta \int_{x_0}^x dx = F \cos \theta (x - x_0) = F \cos \theta \Delta x
 \end{aligned}$$

In one dimension, for a constant force: $W = (F)(\Delta x) \cos \theta$

- $F \rightarrow$ magnitude of force
- $\Delta x \rightarrow$ magnitude of displacement
- $\theta \rightarrow$ Angle between \vec{F} and $\Delta \vec{x}$

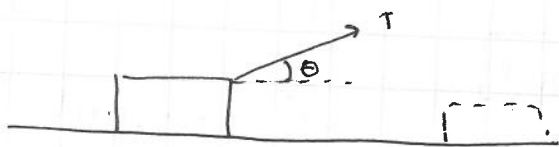
$$W = (F)(\Delta r) \cos \theta \rightarrow \text{constant force}$$

if $0 \leq \theta < 90^\circ$ $W > 0$ Force is adding energy to the System

if $\theta = 90^\circ$ $W = 0$ Force doesn't add or remove energy

if $90^\circ < \theta \leq 180^\circ$ $W < 0$ Force is removing energy from the System

EX



$$W_T = (T)(\Delta x) \cos \theta > 0$$

$$W_n = n(\Delta x) \cos 90^\circ = 0 \text{ J}$$

$$W_{mg} = mg(\Delta x) \cos 90^\circ = 0 \text{ J}$$

$$W_{fk} = (f_k)(\Delta x) \cos 180^\circ < 0$$

RECAP

April, 1, 2019

RECAP CH9.

→ Scalar or Dot Product:

$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos\theta$$
$$= A_x B_x + A_y B_y + A_z B_z$$

→ Basic Energy Model
System
Environment.

$$[W] = [J] = \text{Joule}$$
$$1J = 1Nm = 1 \frac{\text{kg m}^2}{\text{s}^2}$$

$$\Delta E_{\text{system}} = W_{\text{ext}}$$

Total energy
of System

work done by
the environment

$$K = \frac{1}{2}mv^2$$

→ Work \approx KE for a single particle:

$$\int_{x_i}^{x_f} F_x dx = \Delta K = \frac{1}{2}mv_f^2 - \frac{1}{2}mv_i^2$$

Work done by external
force as particle is
displaced from x_i to x_f .

change in kinetic energy of
particle.

→ if there is more than one particle and more than
than one force:

$$W_{\text{total}} = \Delta E_{\text{system}}$$

Sum of work done by all external forces

Recap

April, 1, 2019

$$W_{\text{Total}} = \Delta K \quad \text{if } \Delta E_{\text{th}} = 0$$

Work $W = \int_{x_i}^{x_f} F_x dx$ → Always true

For a constant force → $W = F(\Delta r) \cos \theta$

$$W = F \cdot \Delta r$$

→ only true
→ if \vec{F} is const.

$$W > 0 \quad 0^\circ \leq \theta < 90^\circ$$

$$W = 0 \quad 90^\circ$$

$$W < 0 \quad 90^\circ < \theta \leq 180^\circ$$

Due This week:

Tues: PLC #9 due

Wed: Lab #7 due

Thurs: Ch. 9 HW / Quiz

Ex

$$W_{\text{Total}} = \Delta K = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

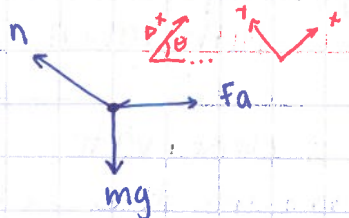
$$0 \rightarrow 10 \text{ m/s}$$

$$10 \text{ m/s} \rightarrow 20 \text{ m/s}$$

$$\begin{aligned} W_{\text{Total}} &= \frac{1}{2} m (10 \text{ m/s})^2 - \frac{1}{2} m (0)^2 \\ &= \frac{1}{2} m (100) \end{aligned}$$

$$\begin{aligned} W_{\text{Total}} &= \frac{1}{2} m (20 \text{ m/s})^2 - \frac{1}{2} m (10 \text{ m/s})^2 \\ &= \frac{1}{2} m (400) - \frac{1}{2} m (100) \\ &= \frac{1}{2} m (300) \end{aligned}$$

Problem 9.4



$$W_{\text{total}} = \Delta k = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

$$W_{\text{Total}} = \frac{1}{2} m v_f^2$$

$$\underbrace{W_n + W_{Fa} + W_{mg}}_{\text{constants}} = \frac{1}{2} m v_f^2$$

$$W = (F)(\Delta r) \cos \theta$$

$$n \rightarrow \theta = 90^\circ$$

$$F_a \rightarrow \theta = 30^\circ$$

$$mg \rightarrow \theta = 120^\circ$$

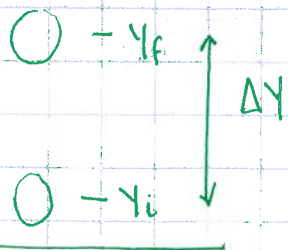
$$\begin{aligned} W_{\text{total}} &= W_n + W_{Fa} + W_{mg} \\ &= (n)(\Delta x) \cos 90^\circ + (F_a)(\Delta x) \cos 30^\circ + (mg)(\Delta x) \cos 120^\circ \\ &= 0 \text{ J} + (20.0 \text{ N})(0.500 \text{ m}) \cos 30^\circ + (3.0 \text{ kg})(9.80 \text{ m/s}^2)(0.500 \text{ m}) \cdot \cos 120^\circ \\ &= 1.31 \text{ J} \end{aligned}$$

$$W_{\text{total}} = \frac{1}{2} m v_f^2$$

$$v_f = \sqrt{\frac{2W_{\text{total}}}{m}} \rightarrow v_f = \sqrt{\frac{2(1.31 \text{ J})}{(3.0 \text{ kg})}} \rightarrow \boxed{v_f = 0.935 \text{ m/s}}$$

Conceptual Question 9.7

Answer:

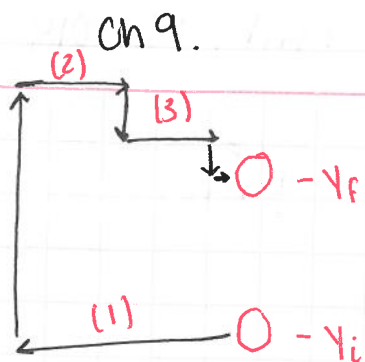


$$\begin{aligned} W &= (F)(\Delta r) \cos \theta \\ W &= (mg)(\Delta Y) \cos 180^\circ \end{aligned}$$

$$\boxed{W_{\text{gravity}} = -mg \Delta Y}$$

True if object moves straight upwards.

April 1, 2019

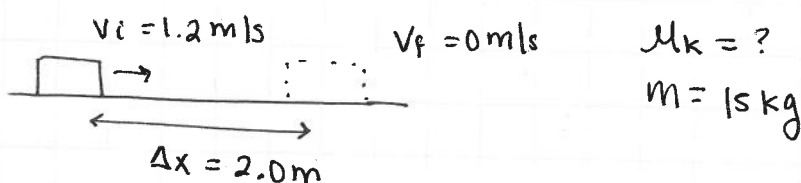


$W_{\text{gravity}} = -mg\Delta y$ regardless of the path taken

gravity is a conservative force which means the work is path independent

$$W_1 = W_2 = W_3 = 0$$

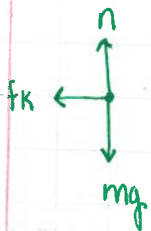
EX Problem 9.33



$$W_{\text{total}} = \Delta K = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

$$W_n + W_{mg} + W_{fk} = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

$= 0$ b/c $\theta = 90^\circ$ $= 0$ b/c $\theta = 90^\circ$ $= 0$



$$W_{fk} = -\frac{1}{2} m v_i^2$$

$$(f_k)(\Delta x) \cos 180^\circ = -\frac{1}{2} m v_i^2$$

$$\mu_k n (\Delta x) (-1) = -\frac{1}{2} m v_i^2$$

$$\mu_k n (\Delta x) = \frac{1}{2} m v_i^2$$

$$\mu_k (mg) \Delta x = \frac{1}{2} m v_i^2$$

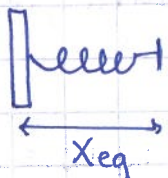
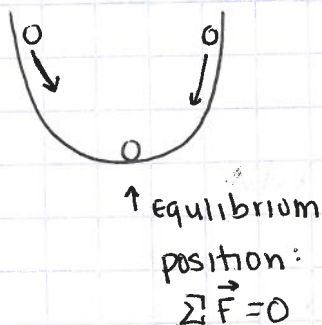
$$\mu_k = \frac{\frac{1}{2} m v_i^2}{mg \Delta x} = \frac{v_i^2}{2g \Delta x} = \frac{(1.2 \text{ m/s})^2}{2(9.80 \text{ m/s}^2)(2.0 \text{ m})}$$

$$\underline{\mu_k = 0.037}$$

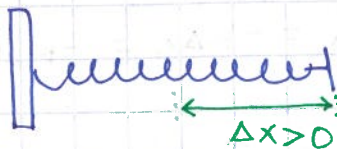
Restoring forces & the work done by a Spring

Restoring force → A force that restores a System to its equilibrium position

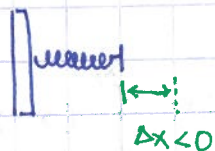
↓ objects that exert restoring forces are called 'elastic'



equilibrium length x_{eq} → length of the Spring when it is unstretched & uncompressed.



→ spring is stretched
if $\Delta x > 0$, Spring exerts a force to the left



→ if spring is compressed
if $\Delta x < 0$, Spring exerts a force to the right

* force (\vec{F}_{sp}) is in the opposite direction to the displacement

* As long as Δx is not too large, $(F_{sp})_x \propto \Delta x$
"force of spring is proportional to Δx "

Hooke's Law → $\vec{F}_{sp} = -k\Delta x$

↓ force Spring exerts Δx → displacement from equilibrium position

$\Delta x = x - x_{eq}$

k → Spring Constant

↳ Number that describes how stiff a spring is

$F = -k\Delta x \rightarrow$ Restoring force
 Could you have a force such that
 $F = k\Delta x$? **NO**

$F = -k\Delta x$
 *since (\vec{F}_{sp}) is not constant, we can not use
 $w = (F)(\Delta r)\cos\theta$

Work done by a Spring: $w = \int_{x_i}^{x_f} F_x dx$

$$(F_{sp})_x = -k\Delta x = -k(x - x_{eq})$$

$$w = \int_{x_i}^{x_f} (-k\Delta x) dx = \int_{x_i}^{x_f} -k(x - x_{eq}) dx$$

$$= -k \int_{x_i}^{x_f} (x - x_{eq}) dx$$

Let $u: x - x_{eq}$
 $\cdot du = dx$

$$w = -k \int_{\Delta x_i}^{\Delta x_f} u du = -\frac{1}{2} k u^2 \Big|_{\Delta x_i}^{\Delta x_f}$$

$$= -\frac{1}{2} k [(\Delta x_f)^2 - (\Delta x_i)^2]$$

$$w_{spring} = - \left[\frac{1}{2} k (\Delta x_f)^2 - \frac{1}{2} k (\Delta x_i)^2 \right]$$

\hookrightarrow work done by a Spring

$$\Delta x_i = x_i - x_{eq}$$

$$\Delta x_f = x_f - x_{eq}$$

RECAP

April 2, 2019

Work & KE for a single particle acted upon by a single force:

$$\int_{x_i}^{x_f} F_x dx = \Delta K = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

For more than one particle and/or forces:

$$W_{ext} = \Delta E_{system} = \Delta K \rightarrow K = \text{sum of kinetic energy of all particles}$$

↓
Sum of work done by all external forces

$$W = \int_{x_i}^{x_f} F_x dx$$

→ Always applies

$$W = F(\Delta r) \cos \theta$$

$$W = \vec{F} \cdot (\Delta \vec{r})$$

} ONLY applies if \vec{F} is constant.

Restoring Forces

- sign indicates direction: \vec{F} is always in the opposite direction of Δx

$$(F_{sp}) = -k \Delta x$$

$$[k] = N/m$$

$$W_{spring} = - \left[\frac{1}{2} k (\Delta x_f)^2 - \frac{1}{2} k (\Delta x_i)^2 \right]$$

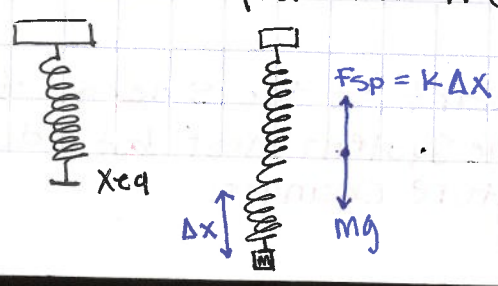
$$\Delta x = x - x_{eq}$$

$$k = 3.50 \text{ N/m}$$

↳ It would take 3.5N of force to stretch the spring 1.0m

(the spring exerts 3.5N of force when it is stretched or compressed by 1.0m)

How would you find k of a spring?



$$\sum F_y = m a_y = 0$$

$$k \Delta x - mg = 0$$

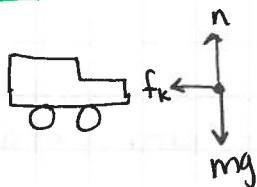
$$k = \frac{mg}{\Delta x}$$

Scribe

$$W_{\text{ext}} = \Delta E_{\text{sys}} = \Delta K$$

→ True for particles that don't interact so kinetic energy is the only form of energy

E_x



$$W_{f_k} = \Delta K = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

$$= -\frac{1}{2} m v_i^2$$

$$f_k \Delta x \cos 180 = -\frac{1}{2} m v_i^2$$

$$\mu_k n \Delta x (-1) = -\frac{1}{2} m v_i^2$$

$$\mu_k (mg) \Delta x = \frac{1}{2} m v_i^2$$

$$v_i^2 = 2 \mu_k g \Delta x$$

$$v_i = \sqrt{2 \mu_k g \Delta x}$$

$$W_{\text{ext}} = \Delta E_{\text{sys}} = \Delta K$$

↳ A macroscopic sized object also has another form of energy called thermal energy E_{th} .

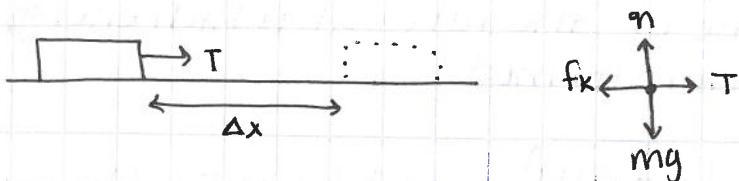
↳ The sum of the microscopic kinetic & potential energies of all the atoms & bonds that make up the object.

Work-energy principle:

$$W_{\text{ext}} = \Delta E_{\text{sys}} = \Delta K + \Delta E_{\text{th}}$$

* When including ΔE_{th} as part of the energy of a system, the definition of the system must include all the objects whose temperature changes.

EX Box pulled across rough floor at a constant velocity



System \rightarrow box + surface

$$W_{ext} = \Delta K + \Delta E_{th}$$

$$\downarrow \begin{matrix} \Rightarrow 0 \text{ b/c} \\ \cos 90^\circ = 0 \end{matrix} \quad \text{(since vel. is const.)}$$

$$W_T + W_{mg} = \Delta K + \Delta E_{th}$$

$$\Sigma F_x = m a_x = 0$$

$$T - f_k = 0$$

$$T = f_k$$

$$T = \mu_k n$$

$$T = \mu_k mg$$

$$W_T = \Delta E_{th} \rightarrow T(\Delta x) \cos 0^\circ = \Delta E_{th}$$

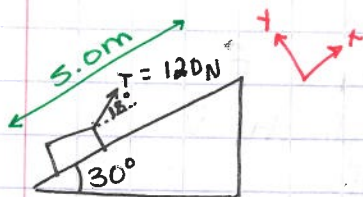
$$T \Delta x = \Delta E_{th}$$

$$f_k \Delta x = \Delta E_{th}$$

derived for this generic example but applies in general.

\hookrightarrow You will use this equation to calculate ΔE_{th}

Problem 34 on book.



$$\mu_k = 0.25$$

$$m = 8.0 \text{ kg}$$

a) W done by T, mg, n?

$$W = (F)(\Delta r) \cos \theta$$

$$W_T = 120 \cdot 5.0 \text{ m} \cos 18^\circ = 0.57 \text{ kJ}$$

$$W_{mg} = -(mg \Delta y) \quad \Delta y = (5.0 \text{ m}) \sin 30^\circ = 2.5 \text{ m}$$

$$= -(8.0 \text{ kg})(9.80 \text{ m/s}^2)(2.5 \text{ m})$$

$$= -0.20 \text{ kJ}$$

OR $W_{mg} = mg(\Delta r) \cos 120^\circ$

$$W_n = 0 \text{ b/c } \cos 90^\circ = 0$$

b) $\Delta E_{th} = f_k \Delta x$

$$= \mu_k n \Delta x$$

$$\Delta E_{th} = (0.25)(308 \text{ N}) \cdot 5.0 \text{ m}$$

$$\Delta E_{th} = 39 \text{ J}$$

$$n = mg \cos \theta - T \sin 18^\circ$$

$$n = (8.0 \text{ kg})(9.80 \text{ m/s}^2) \cos 30^\circ - 120 \text{ N} \sin 18^\circ$$

$$n = 308 \text{ N}$$

Scribe

POWER → Describes the rate at which work is done or the rate at which energy is transformed

$$P = \frac{dE_{\text{sys}}}{dt} \quad \text{or} \quad P = \frac{dW}{dt} \quad [P] = \text{watt } W$$

$$1W \rightarrow 1J/s$$

100 W light bulb → Every second, 100 J of energy are being transformed
(electrical energy → light + heat)

$$P = \frac{dW}{dt}$$

$$W = \vec{F} \cdot \Delta \vec{r}$$

$$dW = \vec{F} \cdot d\vec{r}$$

small amount of work done when force \vec{F} acts over a small displacement $d\vec{r}$
(assuming \vec{F} is constant)

$$P = \frac{\vec{F} \cdot d\vec{r}}{dt}$$

$$= \vec{F} \cdot \frac{d\vec{r}}{dt}$$

$$= \vec{F} \cdot \vec{v}$$

$$P = Fv \cos \theta$$

F → Magnitude of force \vec{F}

v → Magnitude of velocity \vec{v}

θ → angle b/w \vec{F} & \vec{v}

P → Rate at which force \vec{F} is doing work.

Chapter 10: Interactions & Potential Energy April 2, 2019

↳ doing in different order than book ⇒ Simplifying

work-energy principle → $W_{ext} = \Delta E_{syst}$
 $= \Delta K + \Delta U_g + \Delta U_{sp} + \Delta E_{th}$

change in gravitational potential energy change in elastic potential energy